Abstract — The paper summarizes experimental efforts of the Pushkov Institute of Terrestrial Magnetism, Ionosphere and Radio Wave Propagation (IZMIRAN) undertaken in search of the biggest part of Chelyabinsk meteorite in the bottom of Lake Chebarkul, South Ural, and to estimate the ecological effects of its subsequent excavation.

I. INTRODUCTION

The Chelyabinsk meteoroid (February 15, 2013) with an estimated initial mass of about 10,000 tons was probably the biggest space object entering the Earth’s atmosphere during the last 100 years. It released its kinetic energy, equivalent to a 500 kt TNT explosion, into a bright flash at a height of about 25 km (Fig. 1) and a large shock wave causing broken roofs and windows in an almost 100 by 100 km area of Chelyabinsk region. Happily, no industrial object was touched, and hundreds of people received but minor injuries. Many small meteorites produced ice carrots in the snow covering neighboring fields. The biggest part of the meteoroid landed in the western part of Chebarkul Lake making an oval hole in the ice cover, up to 8 m in diameter (Fig. 2). The meteorite origin of the ice-hole was not commonly believed from the beginning, however Raman scattering analysis of the small chips, lifted from the lake bottom with a powerful magnet, and of micron-seized dust around the breach confirmed their space nature [1].

First divers’ attempts to find the meteorite directly under the breach gave no effect. The lake depth is about 10 m at the impact site, and the operations were hindered by the presence of a thick layer of loose silt, more than two-meter thick, according to their estimates. In order to reduce the search area, GPR inspection of the lake bottom was performed from the ice surface by means of Loza-N ground penetrating radar [2-3]. Along with the information provided by Ural scientists and Czech colleagues [4-5], the results of the IZMIRAN-VNIISMI GPR and magnetic surveys were used in preparing diving works undertaken later by the Aleut-Special Work Service Company [6] and resulting in the excavation of the biggest fragment of the space guest.
II. GPR Field Works

Loza GPR was designed at Pushkov Institute of Terrestrial Magnetism, Ionosphere and Radio Wave Propagation (IZMIRAN) in relation with a planned space mission [7]. Afterwards its serial production has been undertaken by Joint-Stock Company VNIISMI [8]. The main distinctive feature of Loza GPR is energy accumulation in a single transmitted pulse which is generated by a capacitor rapidly discharging through a high-voltage hydrogen key. Its duration and shape depend on the transmitter antenna parameters; it must be non-resonant in order to avoid spurious “ringing” (generally, it is a resistively loaded dipole following classical Wu-King law). Due to resistive loading, Loza antenna radiation approaches an ideal one-period electromagnetic burst. Its low Q-factor is compensated by the high pulse energy. Serial Loza transmitters have 5 to 20 kV peak voltage, the emitted pulse duration and energy being determined by the dipole length. Widely used in archeology and urban works “high-frequency” Loza-V sets with 0.5 to 1.5 m antennas have pulse central frequency in the range of 100-300 MHz and provide penetration depth of the order of 5-20 m, depending on ground conductivity.

Fig. 4. Field operation with Loza-V GPR.

In order to radically increase the signal energy and penetration, the pulse spectrum in the low-frequency Loza-N sounder is shifted to the lowest part of the receiver frequency band: 10-50 MHz [9]. A serial Loza-N set contains 3, 6, 10 and 15 meter-long antennas mounted on a heavy-duty nylon band. Identical antennas are used in the receiver unit recording signals reflected from the subsurface layer interfaces or localized buried objects. The receiver works in a waiting mode, being switched on by the first coming aerial signal. The absence of interconnecting cables eliminates interference and assures high signal-to-noise ratio. Loza central unit registers the waveform of the subsurface return pulse by means of a parallel set of high-rate comparators, with sampling frequency about 1 GHz. By repeating the measurement with input attenuation changing in a quasi-logarithmic scale, we obtain a 256-bit representation of the received signal in a 120 dB dynamic range.

Along with the aforementioned basic principles, the tight contact of the Loza-N flexible antennas with the ground and natural wave focusing towards electrically denser subsurface medium increase the GPR penetration depth up. Compared with domestic and foreign analogs, Loza-N radar potential is increased by four orders of magnitude, allowing operation in highly conductive media, such as loam or wet clay. The sounding depth varies from a few meters to hundreds of meters, depending on the device model and medium properties. Taking into account the environment conditions (lake depth about 10 m and 1 m thickness of the ice/snow cover), low-frequency Loza-N model with 6-meter antennas was selected for GPR survey (Fig. 5). It could provide a sufficient probing depth and minimize interfering resonance effects. During three days of field works, March 12-14, 2013, the IZMIRAN-VNIISMI group (A.V. Popov, V.V. Kopeikin, S.V. Merkulov, V.A. Alekseev) recorded 36 GPR scans covering a 100×100 m area around the ice-hole (taking into account the meteorite trajectory, maximum attention was turned to the western neighborhood of the breach) – see Fig.6.

Fig. 5. Starting Loza-N GPR survey from frozen ice-hole (March 12, 2013).

These data, registered from the ice cover, reveal distinct details of the lake bottom shape indicating probable impact points of big meteorite fragments. Small chips were collected around and under the breach in order to identify possible future findings. The results of magnetic moment measurements of 3-millimeter sized chips [1] are consistent with the reported characteristics of other fragments of Chelyabinsk meteorite.
III. DATA ANALYSIS

In Fig. 7, an example of raw data recorded by Loza-N GPR and represented by means of Krot-1301 software [8] is given. The right panel displays the waveform of the radar return signal received at a selected point of GPR survey path (A-scan [10]).

Fig. 7. Example of B-scan and selected radar return pulse (A-scan), Chebarkul lake, March 13, 2013.

In the left panel, the vertical cross-section (B-scan) taken along one of the survey paths is shown. The horizontal axis depicts the distance along the GPR path whereas the vertical axis displays the return signal arrival time in nanoseconds (right scale) and calculated reflector depth (left scale). Peculiar horizontal strips in the upper part of the plot correspond to the direct waves traveling from the transmitter to the receiver antenna with different velocities in the ice layer and pure water beneath the ice cover.

The extended mono-polar pulses coming from greater depths are due to partial reflection from the gradual transition from pure water to the silt layer. Such behavior is typical for the low-frequency Loza-N signals, which previously was attributed to the influence of ground conductivity. However, our numerical simulation shows that the main role in this case plays not conductivity but rather partial EM wave reflections from smooth gradients of the dielectric permittivity arising due to gradual increase of the solid fraction in the thick silt layer. A straightforward approach consists in numerical integration of the 1D wave equation [11]. A good qualitative agreement with the experimental data has been obtained for a model transition layer between pure water with relative dielectric permittivity \( \varepsilon_0 = 81 \) to a solid ground with \( \varepsilon_s = 10 + 20 \), see the left panel of Fig. 8. Our model also took into account a gradual increase of the medium conductivity from \( \sigma_0 = 0 \) to \( \sigma_s = 0.001 \) S/m. The duration of the model probing pulse is about 25 ns, which is close to the physical Loza-N pulse duration.

The full waveform of the electric field registered by the sensitive GPR receiver placed on the water surface is shown in the upper panel of the figure. Along with the short initial pulse, a weak protracted signal appearing due to partial reflections from the vertical gradients of the dielectric permittivity can be noticed (in order to better visualize the reflected signal on the strong primary pulse background, a minor exponential amplification \( \exp(\alpha t) \) has been introduced). Its waveform, shown in a magnified scale against the primary GPR pulse in the bottom panel of Fig. 8, is similar to the observed wave forms of low-frequency GPR probing, depicted in Fig. 7 (not taking into account the direct surface waves). In processing raw data with Krot software package, the characteristic points of the maximum amplitude variations of the reflected signal were interpreted as the interfaces of the non-uniform transition layer between pure water and the solid bottom ground. A qualitative understanding of partial reflections from the vertical permittivity gradients \( \varepsilon'(z) \) gives the time-domain version of the coupled WKB approximation [11]:

\[
 g(s) = -\frac{1}{8} \int_{0}^{\zeta} \left( \varepsilon'(z) \right)^{\gamma} h[s - 2p(z)]d\zeta \tag{1}
\]

Here, \( s = ct \) is normalized propagation time, \( g(s) \) - received EM signal, \( h(s) = \int f(s)ds \) is integral of the initial transmitted pulse \( f(s) \), and \( p(z) = \int \sqrt{\varepsilon(z)}d\zeta \) is optical path from the transmitter to the virtual reflection layer \( z \). If the transmitted pulse length is small compared with the characteristic thickness of the transition layer, the integral (1) can be transformed to an explicit analytical expression [9]:

\[
 g(s) \approx -\frac{1}{8} \left[ \varepsilon' \left( \frac{\varepsilon'}{\varepsilon''} \right)^{\gamma} \right]_{z = z_{\gamma}(s)} \tag{2}
\]
where \( I(s) = \frac{1}{2} \int_0^s \hat{h}(\xi) d\xi \) and \( z_m \) is the depth corresponding to the pulse roundtrip travel time: \( s \approx 2 \rho(z_m) \).

In this simplified 1D wave propagation model a number of the physical moments have been ignored: boundary effects at the water surface covered with a thick ice layer, the offset between the transmitter and receiver antennas, wave divergence and radiation pattern of the dipole antenna placed on the interface. Having taken into account these factors in an improved 2D propagation model we reach a good agreement with the experimental radar scans – see Fig. 9 (a,b), and make our simulation be suitable for the field data analysis.

A standard frequency windowing procedure implemented in Krot-1301 software package allows one to pick out the characteristic points on the signal plot (e.g., maxima of the derivative) and to bind them into a radio image of the reflecting boundaries. Fig. 11 displays an example of such processing distinctly revealing the lake bottom shape and the aforementioned disturbance of the ice cover structure. The interfaces of the transition silt layer between clear water and solid bottom are well seen. The hole produced in the ice cover by the meteorite impact, already frozen during our measurements (March 12-14, 2013), is pointed with black markers at the horizontal axis around the value 110 m. The pronounced depression of the bottom curve, which was interpreted as a result of the meteorite collision with the hard lake bed, is observed 30 m to the west (between 70 and 90 m marks). The local violation of the surface wave structure above the dip can be related to the aforementioned thickening of the ice cover due to the ice mass floated upwards from the impact crater.

IV. PHYSICAL CONSIDERATIONS

A remarkable feature of the GPR B-scan presented in Fig. 7 is a pronounced depression in the bottom curve, accompanied by a local thickening and structure change of the ice cover, in P602 cross-section at its intersection with P603 scan (Fig. 10). We put forward a guess that this anomaly was the result of a meteorite fragment impact onto the lake floor. This hypothesis conforms to the observational facts. The oblique trajectory of meteorite flight with azimuth of 280°–290° and small amount of ejected ice suggest that its major portion might be dragged down by the meteorite west of the hole and then float upward disturbing the structure of the ice cover above the impact crater. On the basis of these considerations, the GPR B-scans were analyzed in detail.

A similar anomaly is observed at the neighboring GPR paths, resulting in a 3D reconstruction of the crater shape [2]. Its position relative to the ice-hole, being consistent with the observational trajectory data, allowed us to recommend searching for a big fragment of Chelyabinsk meteorite in the aforementioned region of the Chebarkul lake floor. Moreover, the spotted 2D pattern of the reconstructed bottom reflectivity (Fig. 12) prompts a suggestion that the meteorite could break into pieces when sinking into the lake water.

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Fig. 10. Aerial photograph of the ice-hole. Crossing of P602 and P603 GPR paths (blue) shows probable meteorite fragment position in the lake bottom; red marks - six stakes around the breach.

Fig. 11. B-scan along P602 track, processed with Krot-1301

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V. MAGNETOMETRY AND METEORITE RECOVERY

Basing on the expected magnetic nature of the Chebarkul meteoroid fragment, several research groups performed magnetometric surveys of the supposed impact site. Just a week after the meteorite fall, February 20-21, 2013, A.V. Ovcharenko and V.A. Shchapov (Institute of Geophysics, Ural Branch of the Russian Academy of Sciences) performed magnetic mapping of the ice surface around the frozen ice-hole [4]. An overall distribution of the modulus of magnetic induction is presented in Fig. 13.

The authors call the reader’s attention to a weak positive horseshoe-like anomaly ~ 5-6 nT about 20 m west of the breach, which ‘might be caused by the main fragments of the hondrite body’. A strong negative linear anomaly of 40-50 nT, south-east of the ice-hole, evidently has no relation with the meteorite body and may have man-caused nature.

Two weeks later, a research group from the Charles University, Prague, led by G. Kletetschka, made surface magnetic field mapping showing a positive anomaly to the north-west of the breach that was interpreted as a purely geological effect [5]. The subsequent underwater magnetic survey with a submersible fluxgate magnetometer, performed in June 2013, revealed two sharp peaks of magnetic induction, south-east of the ice-hole - see Fig 14. However, these anomalies, centered at the 9 m depth, also might have technogenic origin.

The second IZMIRAN mission (S.A. Gudoshnikov, V.S. Skomarovskij, V.B. Buzin, V.A. Alekseev, April 2-5, 2013) performed magnetic survey of a rectangular portion of the ice surface 80x30 m to the west of the ice-hole. The raw data (Fig. 15) exposed a regular increase of magnetic induction towards the west (coast effect, analogous to Fig. 14).

By subtracting the westward trend we obtain a map of local magnetic anomalies (Fig. 16) having much in common with the pattern of GPR back reflections (Fig. 12). This similarity supported our guess at the meteorite fragments position in the lake bottom ground.

The results of the first IZMIRAN-VNIISMI GPR and magnetic surveys were submitted to the Ministry of Ecology of the Chelyabinsk Region Government having sponsored the diving works undertaken during September-October 2013 by the Aleut-Special Work Service Company [6] – Fig. 17.
The underwater works ended up in finding and digging up a 654 kg meteorite fragment. These endeavors are vividly depicted in the recently published book [12]. According to the data presented by N.E Murzin, Head of Aleut Company, the biggest piece has been extracted from the depth of about 18 m, some 10 meter south-west of the breach. The main excavated meteorite fragment now is exposed in the Chelyabinsk Lore museum – Fig. 18. Its smaller parts, broken away during the diving works, have been presented to different organizations that took part in the search for the meteorite [13].

Raman scattering analysis of the fragment presented to IZMIRAN, performed by N.N. Melnik (FIAN) [14], confirmed its mineral composition corresponding to ordinary chondrite LL5 and spectral identity with the small meteorite chips gathered from the ice cover and the bottom of Lake Chebarkul immediately after the meteorite fall – see Fig. 19.

Taking into account the continuing interest to the Chelyabinsk event, ecological concerns about Lake Chebarkul condition and methodical problems of GPR measurements from the water surface, four years later the third IZMIRAN GPR mission was organized (D.E. Edemskij, A.V. Popov, I.V. Prokopovich, L.A. Bogolyubov, June 15-22, 2017). The main goal of the planned survey was to draw the bottom line left after the Aleut diving works and to detect possible subsurface objects. In order to provide better spatial resolution we should use shorter antennas. Basing on our previous experience, we first tried a standard Loza-V GPR transmitter and antenna set (Fig. 4) assuring 10-12 m penetration in a fresh lake water [15]. All the equipment could be placed in a hull of a small rowing boat allowing convenient through-water operation along a chaotic path controlled by GPS. Unfortunately, the tests performed in the vicinity of the meteorite impact site (west coast of Lake Chebarkul) had shown worse penetration, making Loza-V set useless at the depths exceeding 5 m – see Fig. 20.
\( \sigma \approx 0.066 \) S/m, which is in a good agreement with the hydrological data obtained after the meteorite fall [16].

Trying to overcome this limitation, we developed a home-made antenna set of intermediate (4 m) size but heavy rain storms did not allow us to complete the 1. experiment.

![Fig. 21. Testing 4-m dipole antennas](image)

**VI. CONCLUSION**

The results of the first IZMIRAN-VNIISMI GPR survey (March 12-14, 2013) and the data of magnetic measurements performed by the next IZMIRAN expedition (April 2-5, 2013) from the ice surface revealed a pronounced anomaly, west of the breach left after Chelyabinsk meteorite fall into Lake Chebarkul (February 15, 2013). Along with other research groups’ data, they were used in preparing diving works undertaken during September 2013 by 5. the Aleut-Special Work Service Company and sponsored by the Chelyabinsk Region Government. These works resulted in finding and lifting a big fragment of the meteorite (October 13, 2013). A part of the excavated space body presented to IZMIRAN 6. was put to Raman scattering analysis at Lebedev Physical Institute (FIAN), conforming its mineral composition corresponding to ordinary chondrite (LL5). GPR survey performed by the third IZMIRAN mission (December 18-20, 2013) revealed a sharp dip in the lake bottom, probably a result of the digging operation. An attempt of detailed GPR inspection of the lake bottom undertaken in June 2017 did not give impressive results because of high conductivity of the lake water and bad weather conditions. However, among others, our GPR data and magnetic measurements prompt that a considerable mass of the meteorite matter may still reside in the Lake Chebarkul bottom ground.

**ACKNOWLEDGMENT**

This publication is dedicated to the memory of Vladimir Alekseev who participated in two IZMIRAN expeditions, collecting small meteorite particles and performing their physical-chemical analysis.

The authors are grateful to E.V. Korolkov and Chebarkul City Administration for technical support of the field works.

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